

MICRO-428: Metrology

Week Eleven: Electrical Metrology

Alexandre Domenech

Samuele Bisi

Claudio Bruschini

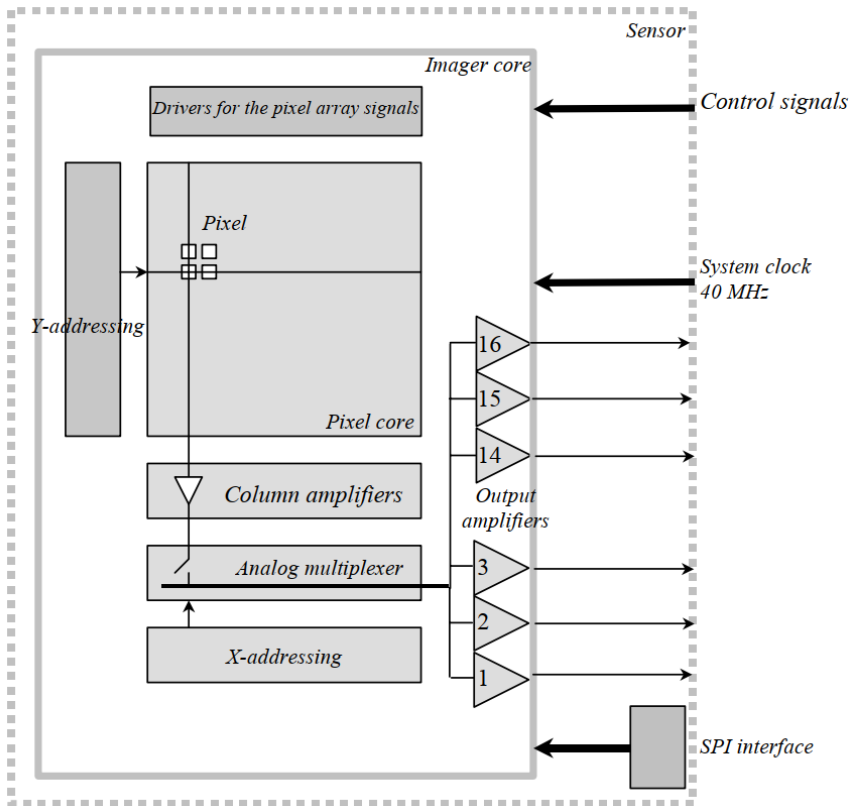
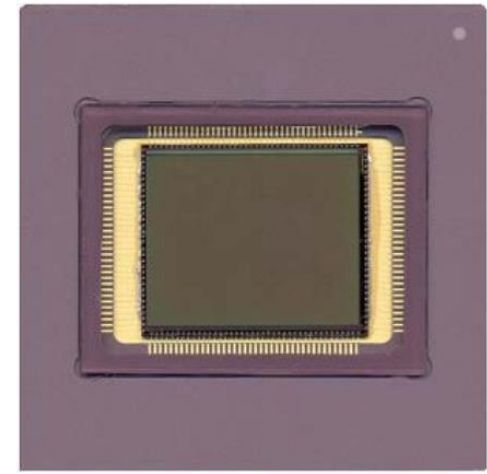
Advanced Quantum Architectures Laboratory (AQUA)

EPFL at Microcity, Neuchâtel, Switzerland



Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



Relevant information derived from the specifications are:

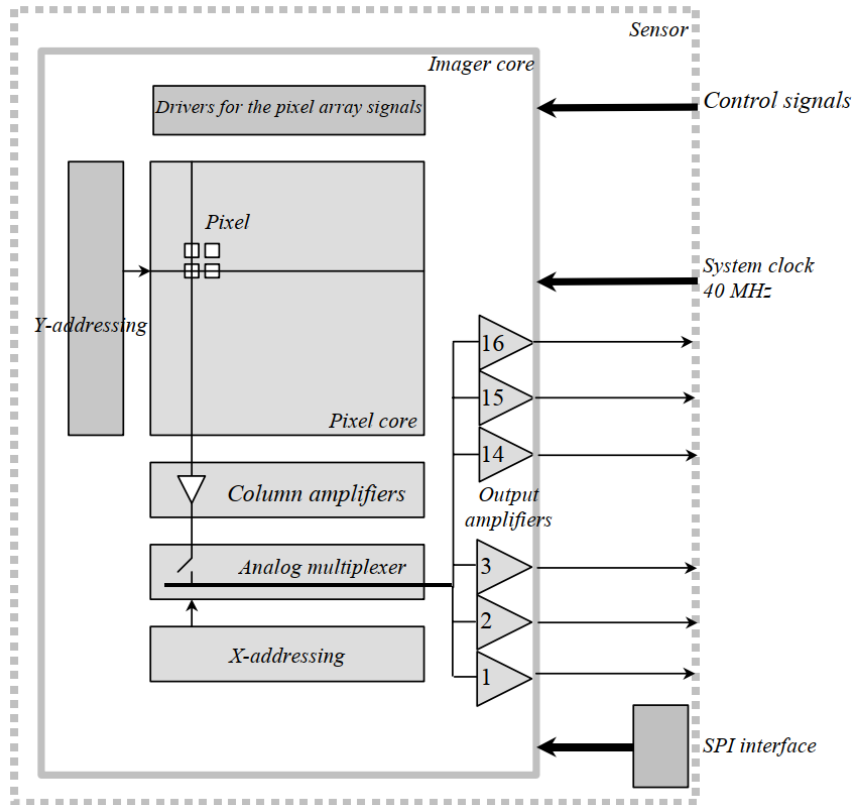
- **1280×1024** pixels, each **14 μm square**.
- Full well capacity: **62500** electrons.
- Output at **60,000** electrons: **1 V**.
- Typical quantum efficiency across the visible spectrum: **15%**.
- Dark current and read noise: **45 e^-/pixel**
- Recommended clock speed (pixel read rate): **40 MHz**

Output read by **16 parallel amplifier** channels (so each channel only looks at an **80×1024 subarray**).

 https://www.asdlib.org/onlineArticles/elabware/Scheeline_ADC/

Exercise 1: Video digitization

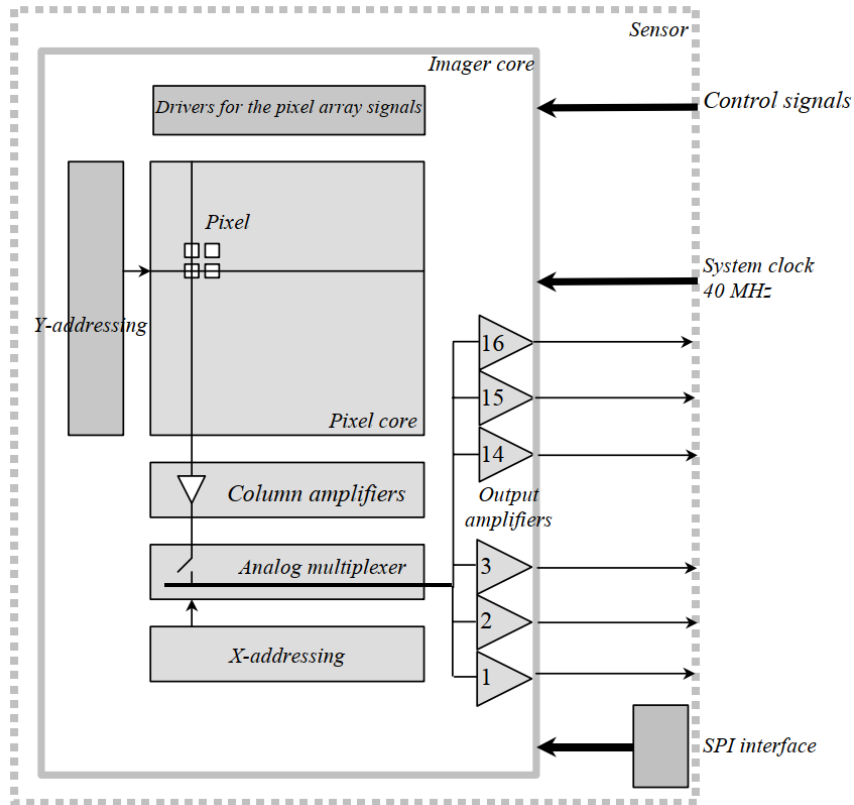
- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



1/ What is the appropriate number of bits for resolution?

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



1/ What is the appropriate number of bits for resolution?

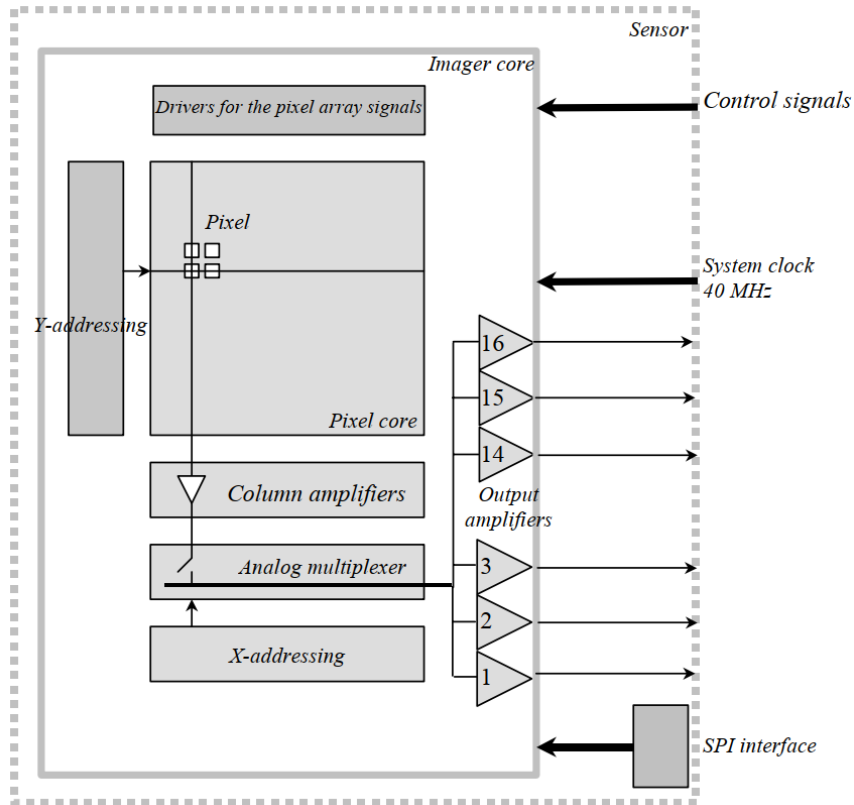
Maximum limit: Full scale is 62500 electrons, so even if there were no noise, the biggest useful number would be just short of $65536 = 2^{16}$.

Minimum limit: The dark current and read noise come to $45 e^-$, the shot noise limit is thus $\sqrt{45} e^-$, meaning that each digitization has an uncertainty of 6-7 electrons => The highest useful count is: $62500/6 = 10411$ counts, that's between 2^{13} and 2^{14} .

Choosing 1 bit amplitude = 7 electrons, then the appropriate number of bits for the ADC are **14 bits**.

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics

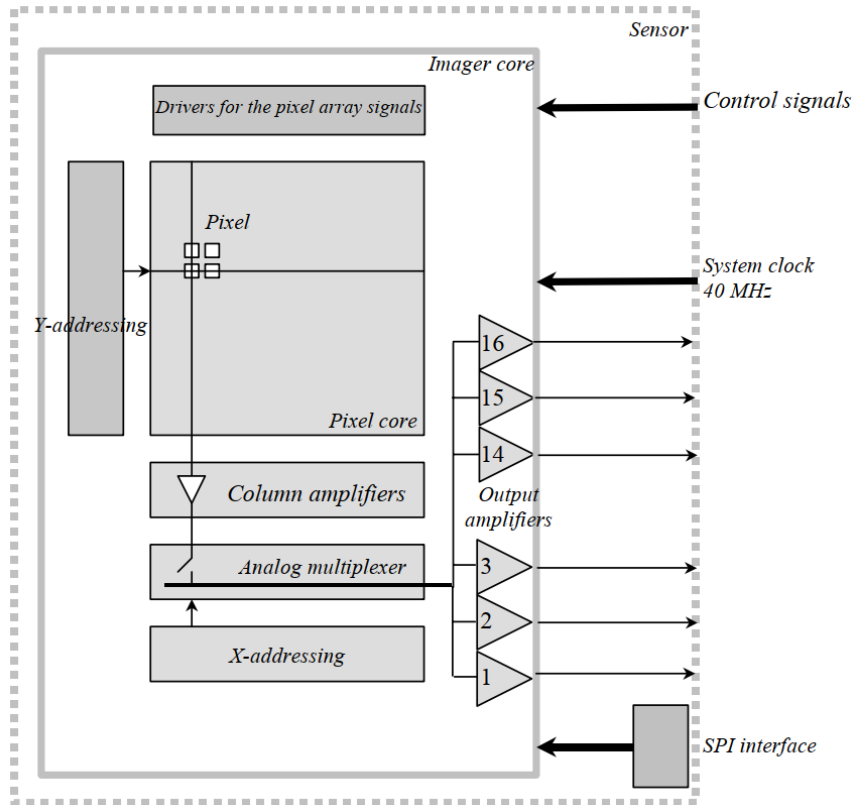


2/ What is the required number of ADC conversions per second?

Hint: Each ADC is dedicated to a single channel. The problem specifies the conversion rate per channel, which makes it possible to calculate the number of pixels associated with that particular channel.

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



2/ What is the required number of ADC conversions per second?

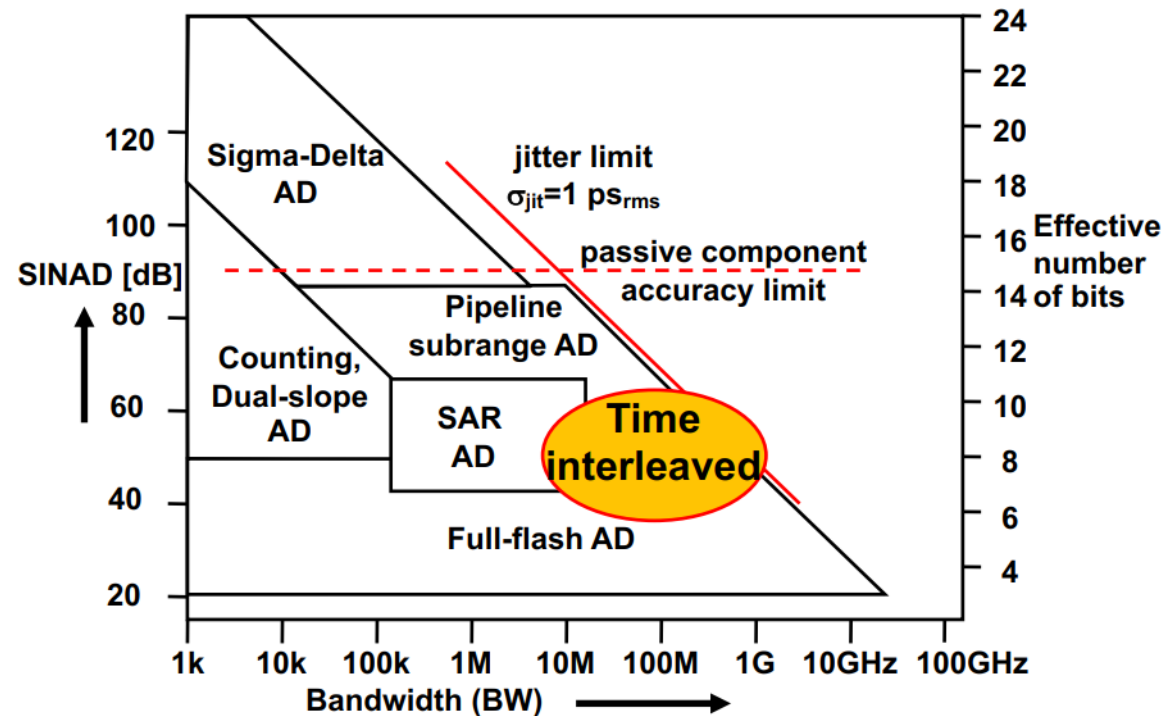
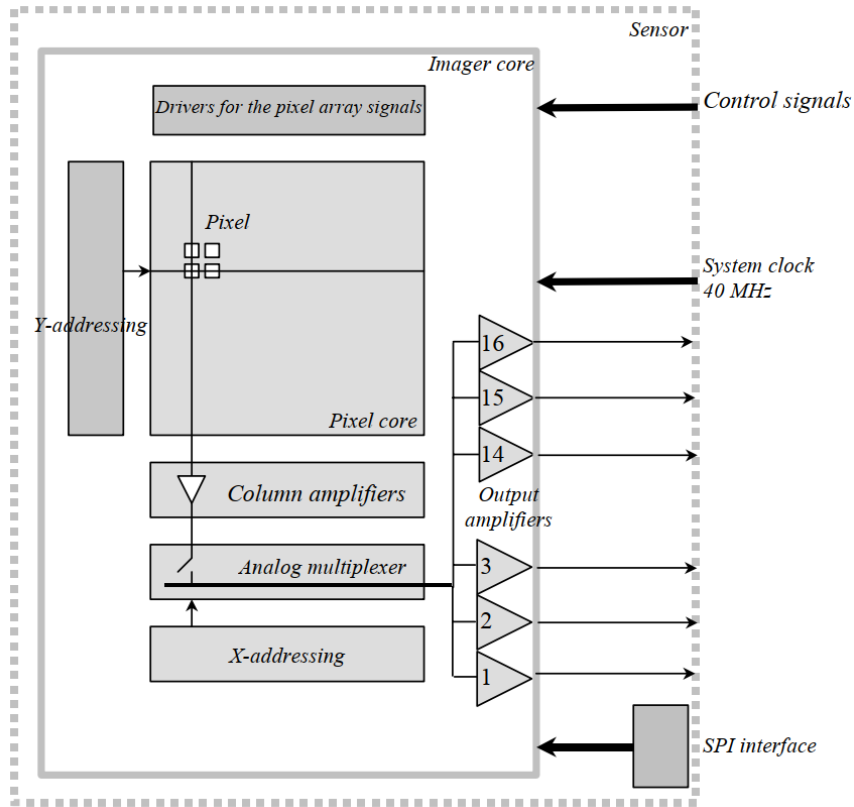
Hint: Each ADC is dedicated to a single channel. The problem specifies the conversion rate per channel, which makes it possible to calculate the number of pixels associated with that particular channel.

Considering that the optimal clocking speed of the array is **40 MHz**, each channel must perform digitization at the same speed. Each channel is responsible for analyzing **80×1024 pixels**, which corresponds to **81920 pixels**. Consequently, we can digitize the output of the array at a frequency of **$4 \times 10^7 / 81920 = 488$ Hz**.

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics

3/ Which ADC type would you suggest using?



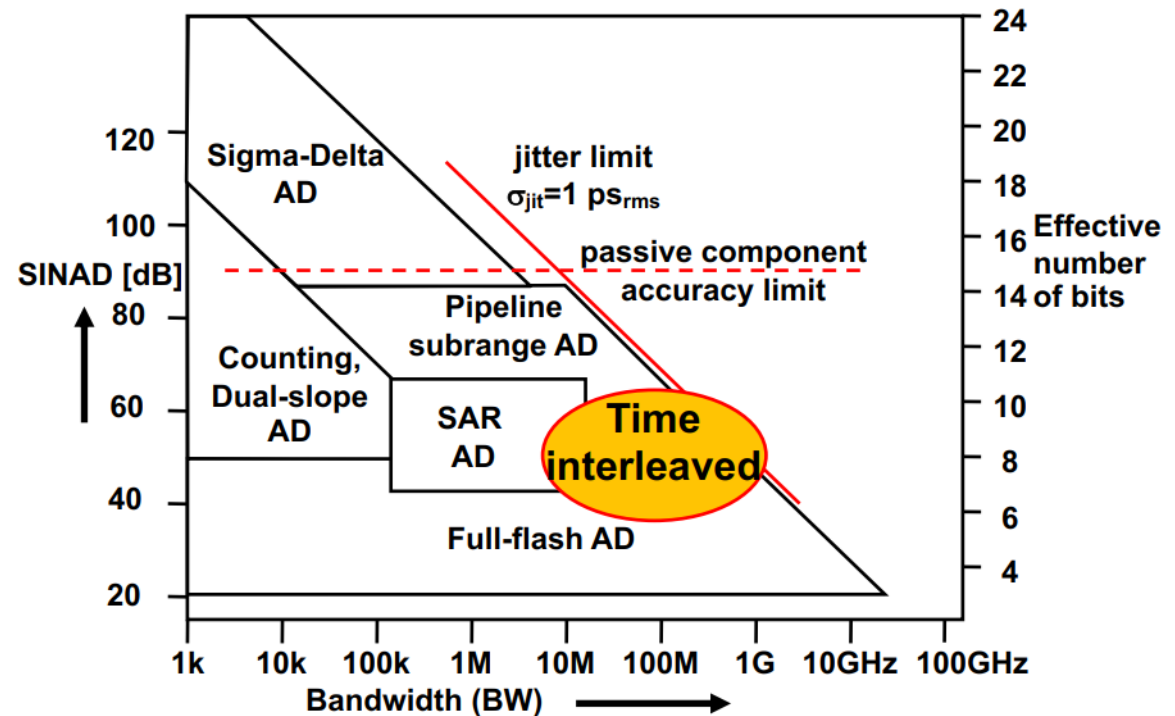
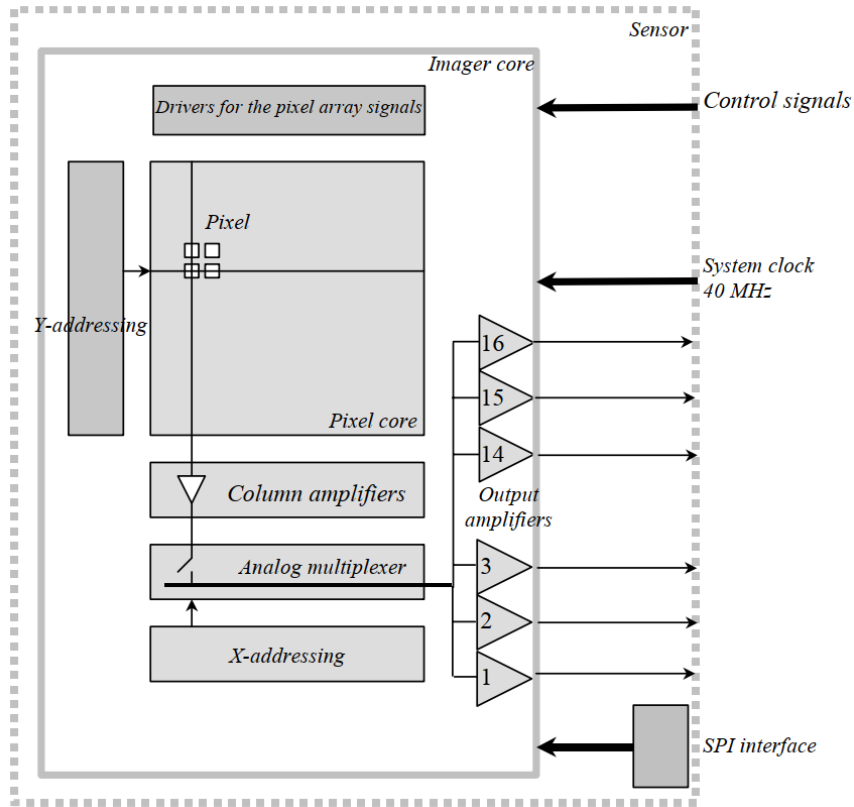
Mead courses, "Data converters", 2021

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics

3/ Which ADC type would you suggest using?

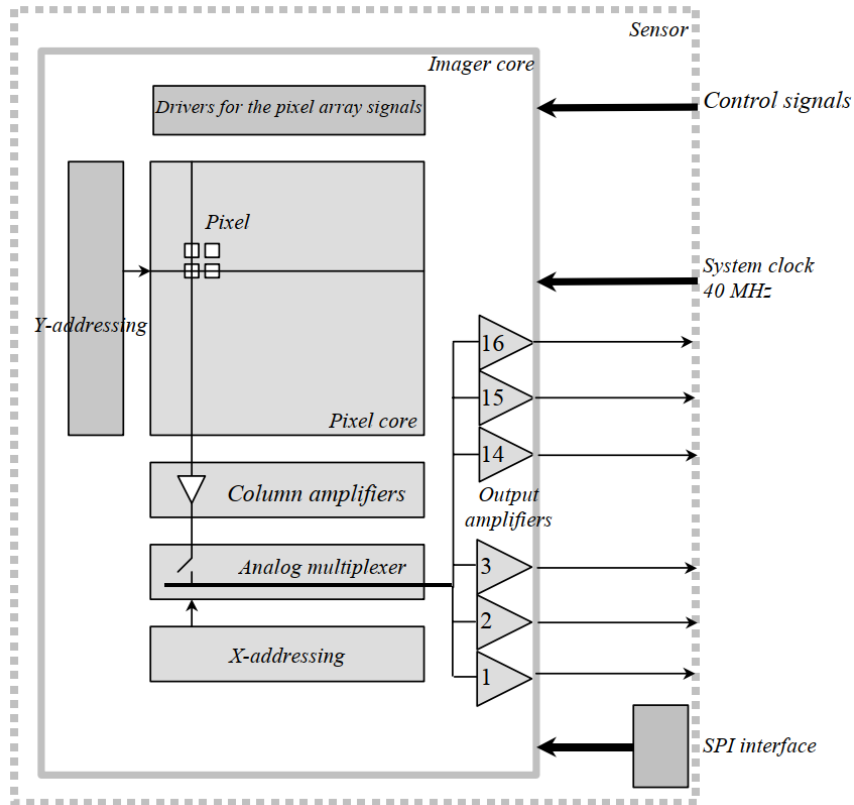
We must either use a 14-bit ADC that can function at a speed of 40 MHz, or reduce the output rate.



Mead courses, "Data converters", 2021

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics

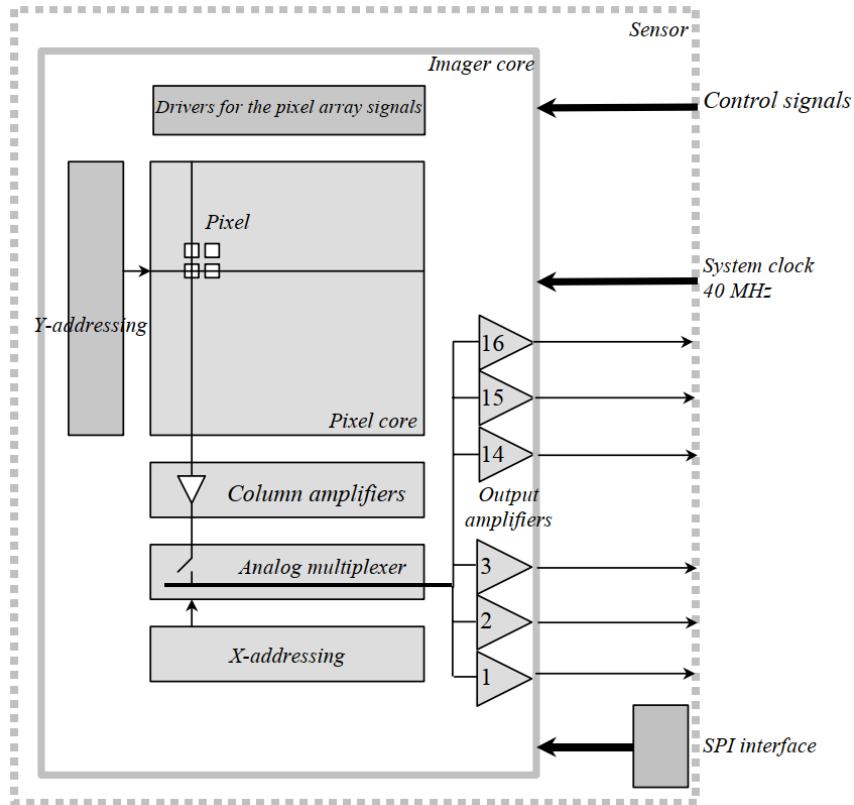


4/ What would be the signal-to-noise ratio (SNR) of an intensity measurement for a single read cycle?

Hint: Let's examine different sources of noise. Even if the ADC had infinite resolution, we would still encounter shot noise and readout noise. Which of these noise sources is the most significant?

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



4/ What would be the signal-to-noise ratio (SNR) of an intensity measurement for a single read cycle?

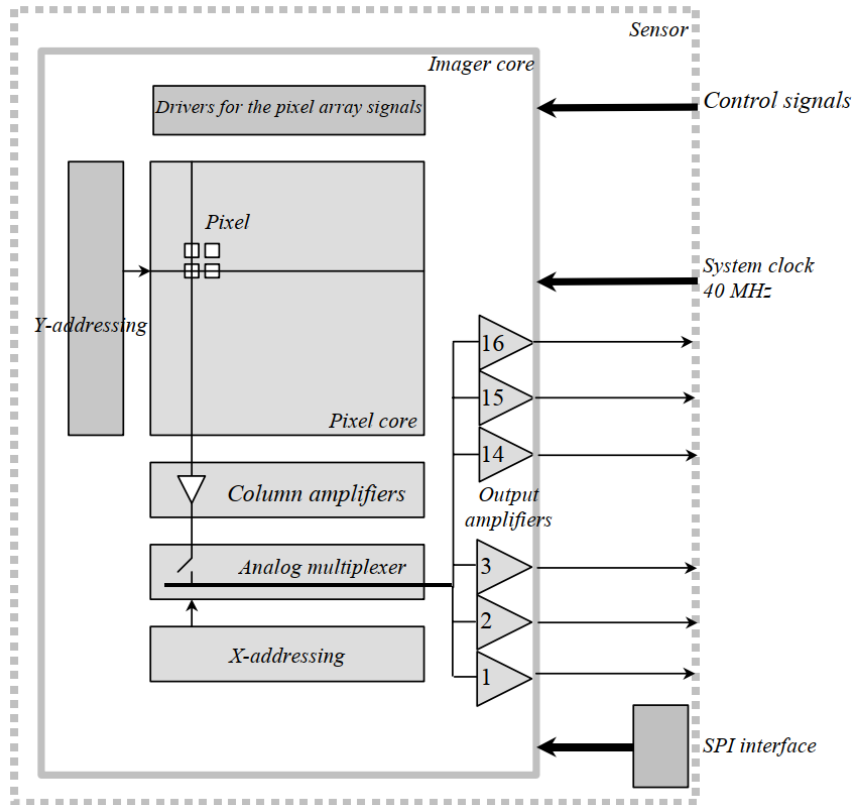
Hint: Let's examine different sources of noise. Even if the ADC had infinite resolution, we would still encounter shot noise and readout noise. Which of these noise sources is the most significant?

- If there is no signal $\rightarrow S/N = 0$
- When the signal reaches full $\rightarrow S = 62500 e^-$. The noise sources are: Shot noise $\sqrt{S} = 250 e^-$, and dark current/read noise = $45 e^-$. At a first approximation: $S/N = 62500/250 = 250$. To be more rigorous, we can express the total noise assuming that the noise sources are uncorrelated as:

$$\sigma_{total} = \sqrt{\sigma_{full\ scale}^2 + \sigma_{dark/read}^2}$$

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics

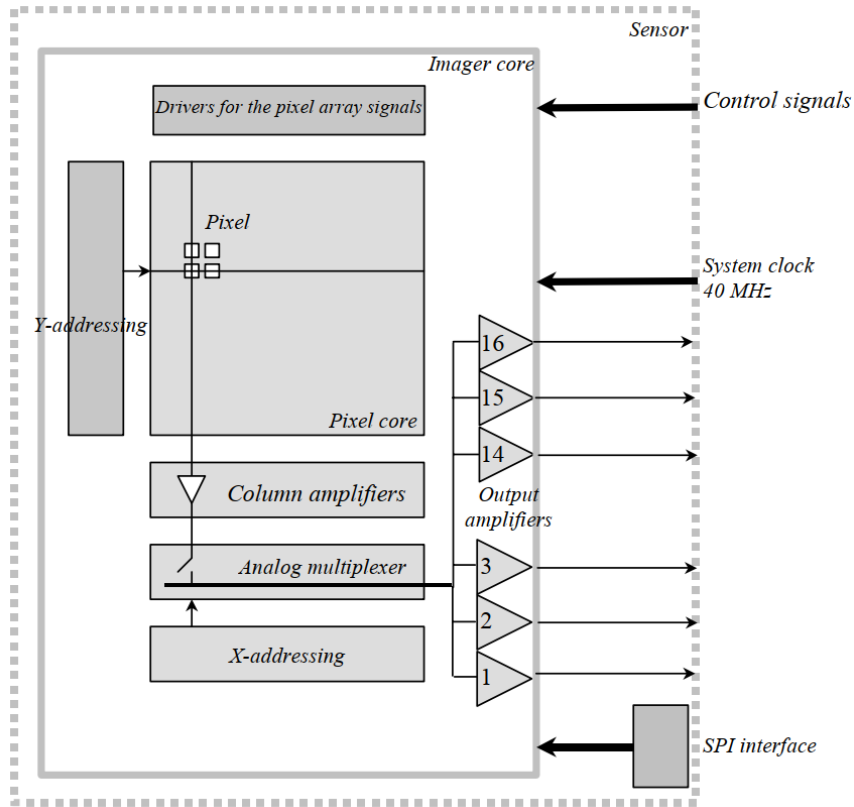


5/ What would be the new SNR value if we average all the data for 1 second?

Reminder: The new standard deviation of the mean can be calculated by dividing the original standard deviation by the square root of the number of measurements averaged (N)

Exercise 1: Video digitization

- The objective is to determine the appropriate ADC to utilize in a cell phone camera alongside a CMOS array. An instance of a high-speed CMOS sensing chip is the LUPA-1300 from Cypress Electronics



5/ What would be the new SNR value if we average all the data for 1 second?

Reminder: The new standard deviation of the mean can be calculated by dividing the original standard deviation by the square root of the number of measurements averaged (N)

The uncertainty for a single full-scale read is **250 electrons**, and since there are **488 reads** per second, the uncertainty can be reduced by averaging the measurements. Using the formula for the standard deviation of the mean, the uncertainty of the mean for **488 reads** is reduced to approximately **22 electrons**, which is an **improvement in signal-to-noise ratio by a an order of magnitude** compared to a single read.

Exercise 2: Group explanation

1. Divide yourself in small groups (2-3 ppl).
2. Discuss the following example taken from the lecture, focusing on understanding what is happening.

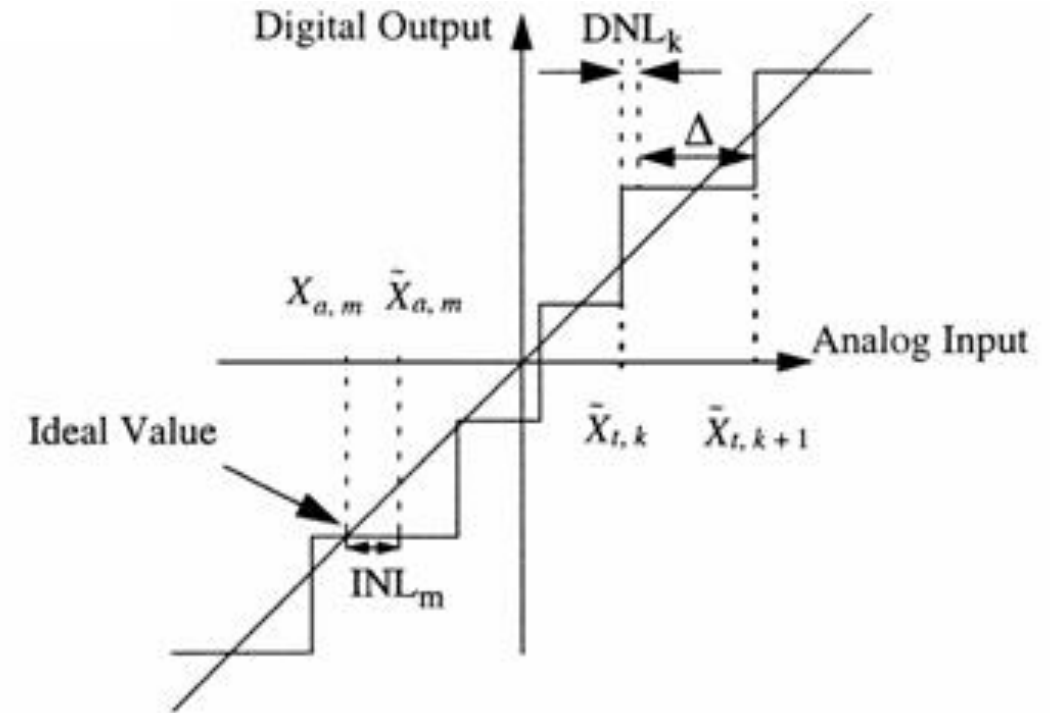
5.2.2 ADC – Real Case

- Non-idealities:
 - Differential non-linearity (DNL)
 - Integral non-linearity (INL)

$$DNL_j \equiv \frac{Width_{ACTUAL,j} - Width_{ID}}{Width_{IDEAL}}$$

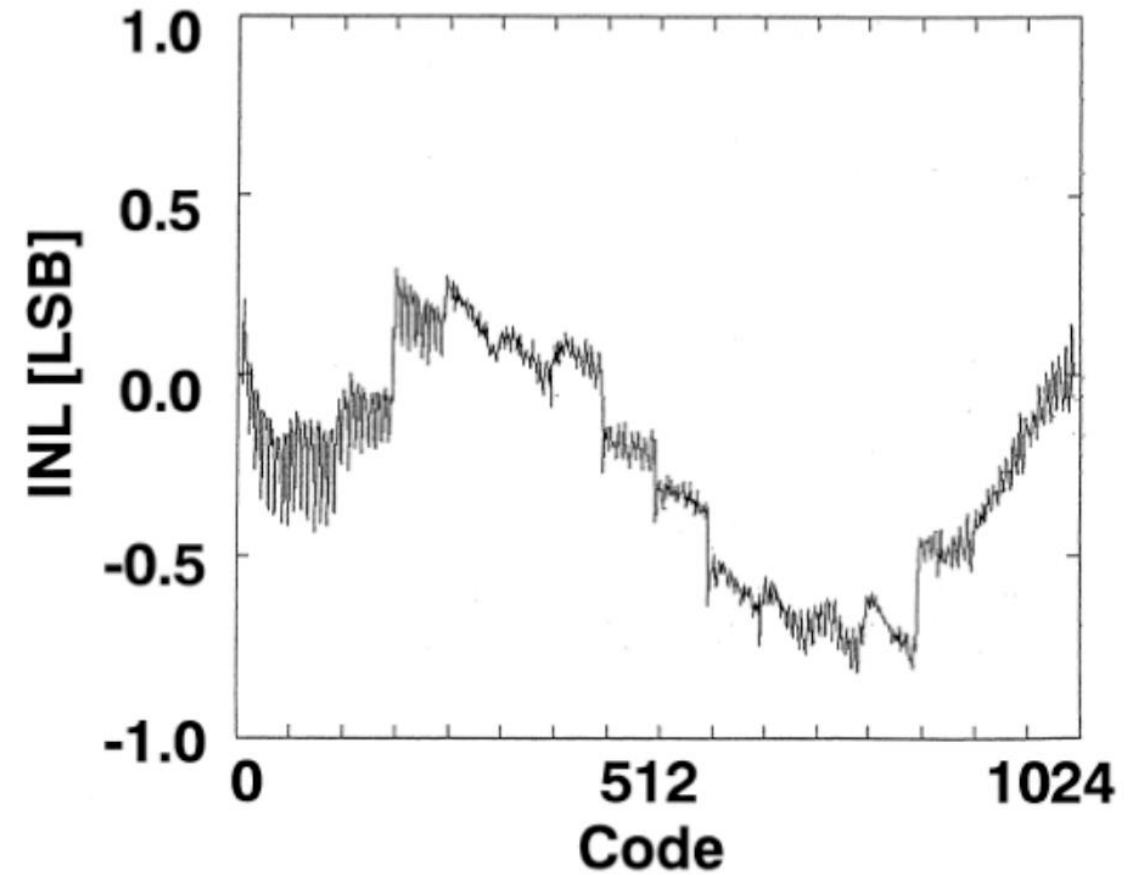
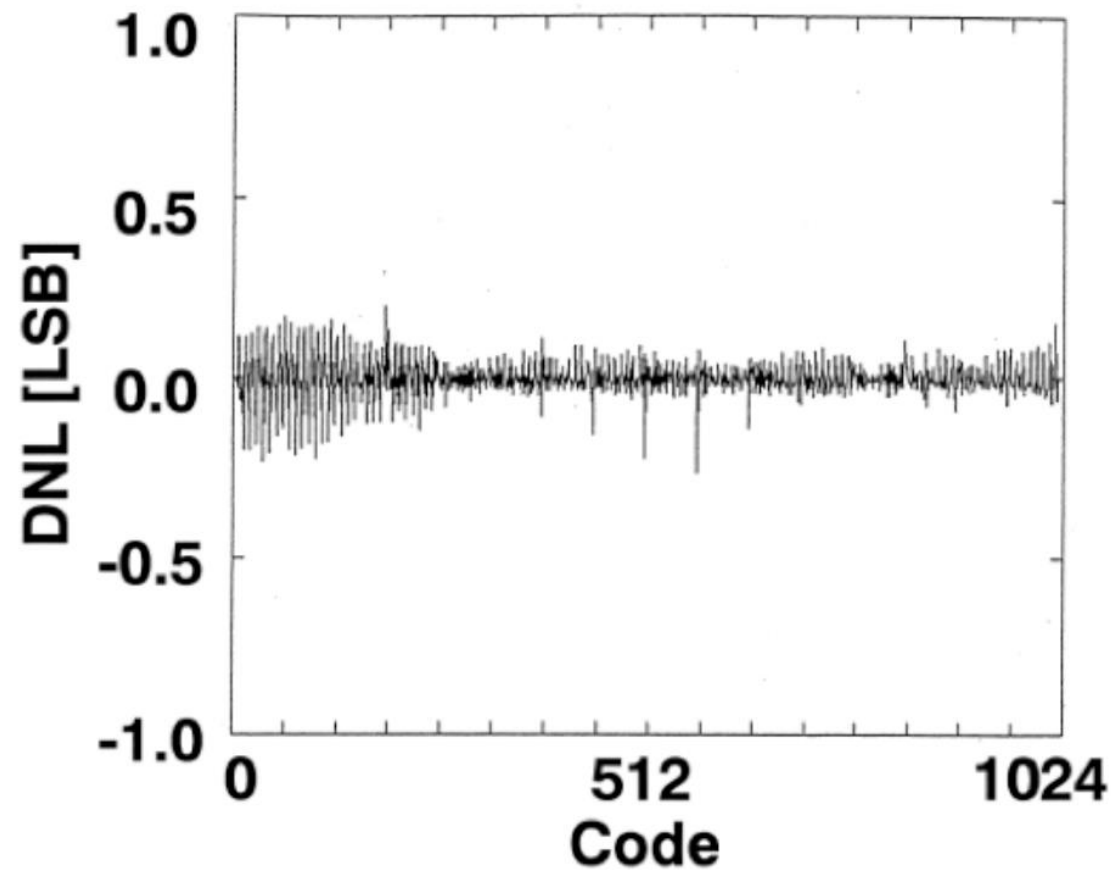
$$INL_j = \sum_{k=0}^{k=j} DNL_k$$

$$DNL_j = INL_{j+1} - INL_j$$



INL = deviation of transfer curve from ideal (linear)

5.2.2 ADC – Real Case, Example



Source: A. Matzusawa

5.2.2 ADC architectures

- Divide yourself in small groups (2-3 ppl).
- Select two ADC architectures and explain them to your colleagues

5.3 TDC architectures

- Divide yourself in small groups (2-3 ppl).
- Select two TDC architectures and explain them to your colleagues

Exercise 3: Choosing the right architecture

By group of 2-3 pick the right ADC and justify your choice.

Trait / Application

Matching ADC Type

1. Fastest possible conversion speed
2. Uses a binary search algorithm
3. Low power, moderate speed, good resolution
4. Uses an integrator and a counter
5. Requires one comparator per output level (2^n levels)
6. Often used in digital multimeters
7. Uses capacitor array for successive charge balancing
8. Best suited for audio applications (e.g., microphone)
9. Has the smallest latency
10. Balanced in speed, area, and resolution

Exercise 3: Choosing the right architecture

By group of 2-3 pick the right ADC and justify your choice.

Trait / Application	Matching ADC Type	Justification
1. Fastest possible conversion speed	Flash ADC	All comparisons are done in parallel; no iteration, ideal for GHz-speed systems like video or radar.
2. Uses a binary search algorithm	SAR ADC	SAR uses a DAC and comparator iteratively to zero in on the input value.
3. Low power, moderate speed, good resolution	SAR ADC	Efficient architecture with low switching activity and few analog blocks.
4. Uses an integrator and a counter	Integrating ADC	Dual-slope and sigma-delta ADCs integrate input over time before converting.
5. Requires one comparator per output level (2^n levels)	Flash ADC	Needs $2^n - 1$ comparators for n-bit resolution → fast but area and power intensive.
6. Often used in digital multimeters	Integrating ADC	High noise immunity and precision over long integration time; ideal for slow, accurate readings.
7. Uses capacitor array for successive charge balancing	Charge Redistribution ADC	SAR variant with a binary-weighted capacitor DAC; offers compact design.
8. Best suited for audio applications (e.g., microphone)	Integrating ADC (Sigma-Delta)	Sigma-Delta oversampling filters out noise; great linearity and dynamic range for audio.
9. Has the smallest latency	Flash ADC	One clock cycle latency — perfect for real-time high-speed applications.
10. Balanced in speed, area, and resolution	SAR / Charge Redistribution	SAR (esp. capacitor-based) gives a sweet spot for medium-performance systems (MCUs, sensors).

Exercise 4: Group explanation

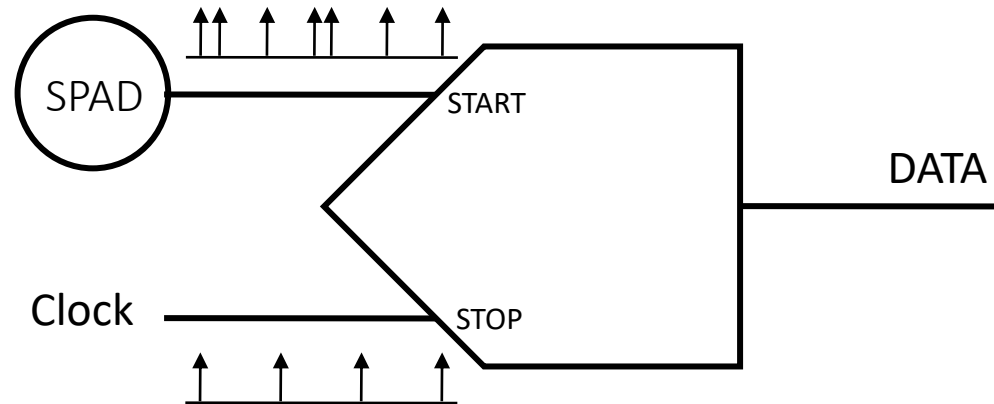
1. Divide yourself in small groups (2-3 ppl).
2. Discuss the following TDC-related Metrology techniques – code-density test and single-shot experiment – focusing on understanding what is happening.

5.3 TDC – Metrology: Optical Tests

A) (Code) Density test: free running SPAD (e.g. natural light source)*

B) Single-shot experiment (e.g. repetitive pulsed laser illumination):

- Histogram $\Delta t_i, i=[1...N]$ (Time-correlated single-photon counting – TCSPC)



*could also be done electrically

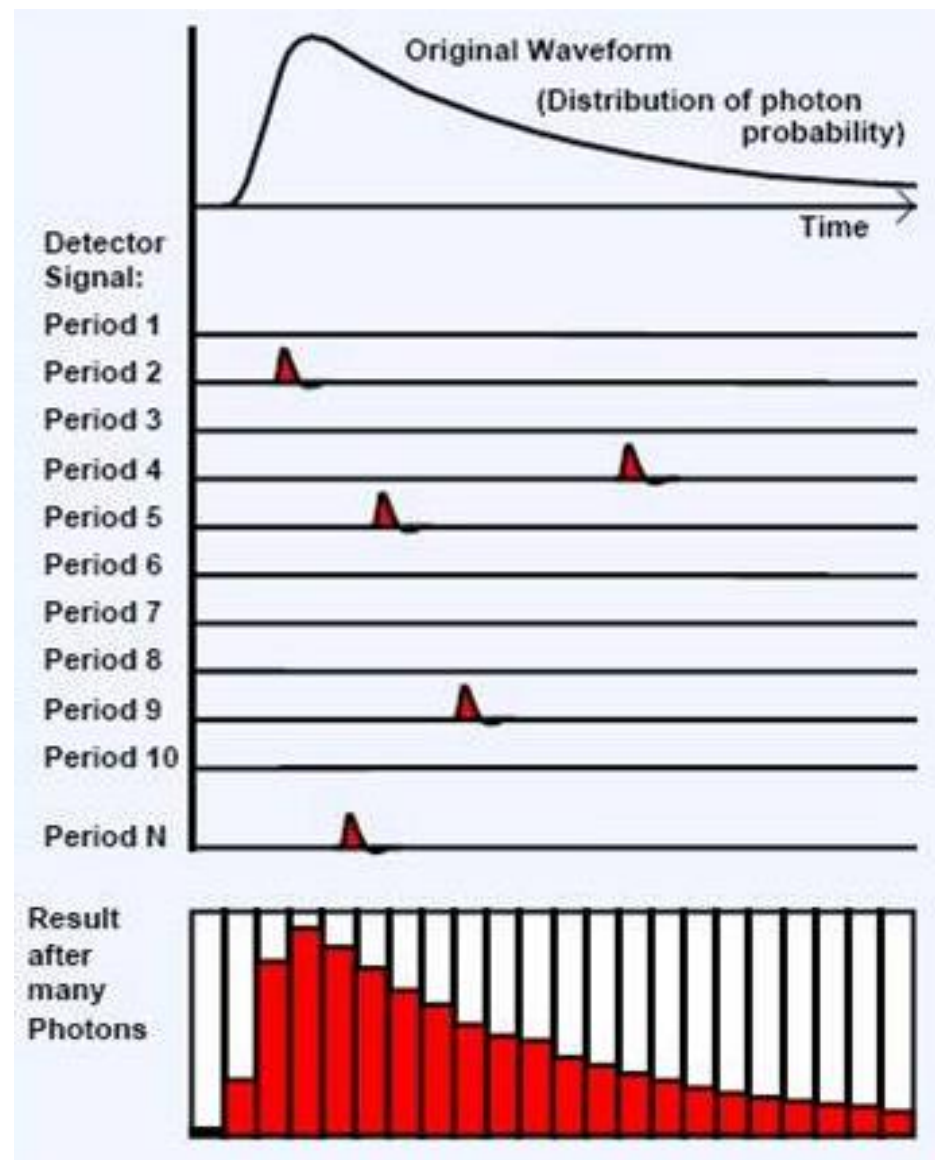
Homework

Homework 1-3 have already been discussed in previous classes and can be relevant to the exam.

Homework 1: Design and analysis of a FLIM System

- Design and analyse a simple Fluorescence Lifetime Imaging (FLIM) system, based on the discussion during the class (TDC application examples, Section 5.3.9):
 - a) Estimate the overall system parameters (e.g. fluorophore type, typical process timescales, detector and excitation source). How do their variances add?
 - b) Which is the PDF/CDF of the fluorescent sample?
 - c) How can you estimate the fluorescence lifetime from i) a timestamp histogram, ii) a series of timestamps?
 - d) Which is the standard deviation of the fluorescence lifetime and how does it get better with increasing sample size?
 - e) Suppose that there are two fluorophores with different lifetimes (e.g. 2 and 4 ns) and that your measurement system is ideal (negligible measurement error). How many measurements are necessary to differentiate them (rough estimate)?
- *Hint:* Use a Time-Correlated Single-Photon Counting (TCSPC) approach

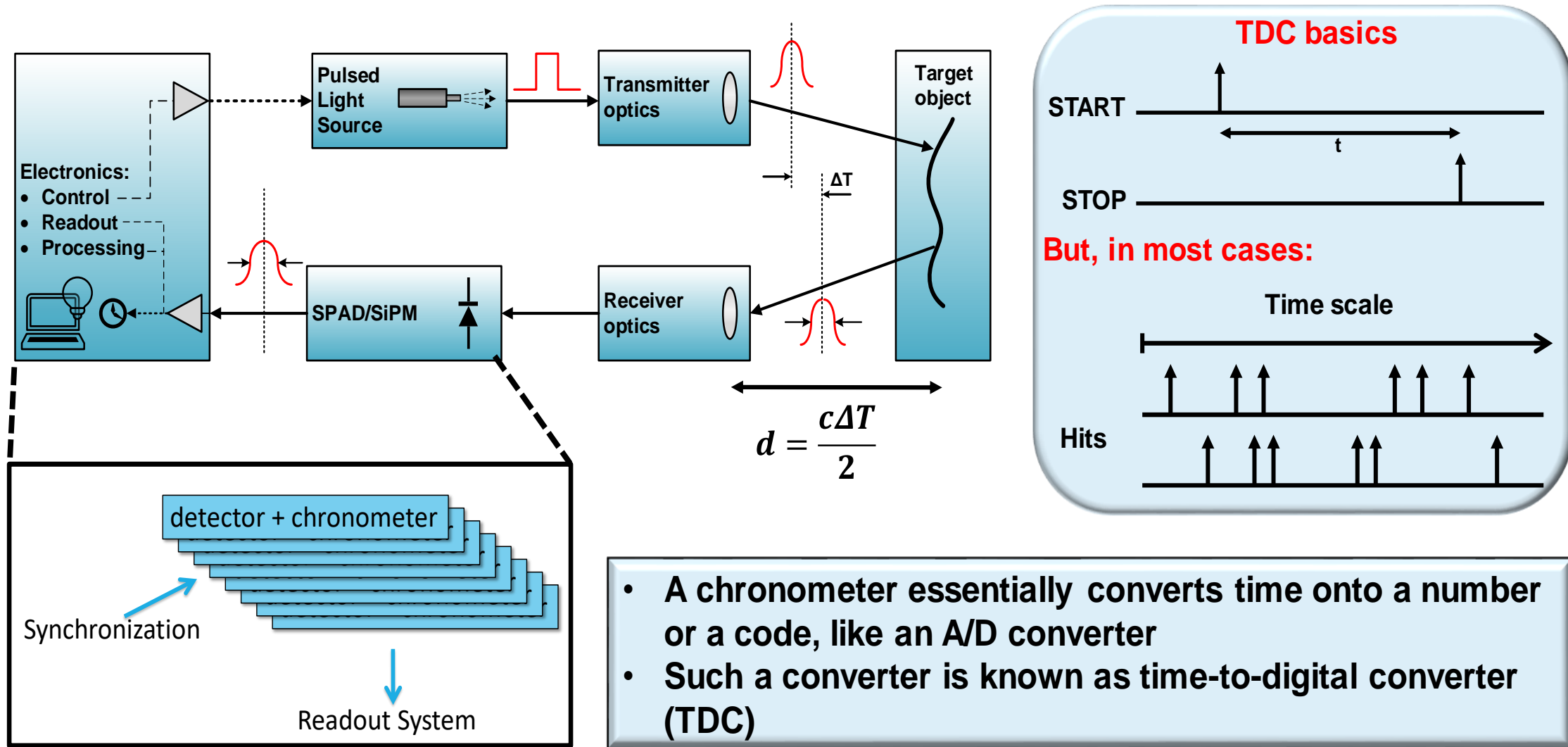
Homework 1: Reminder: TCSPC Principle



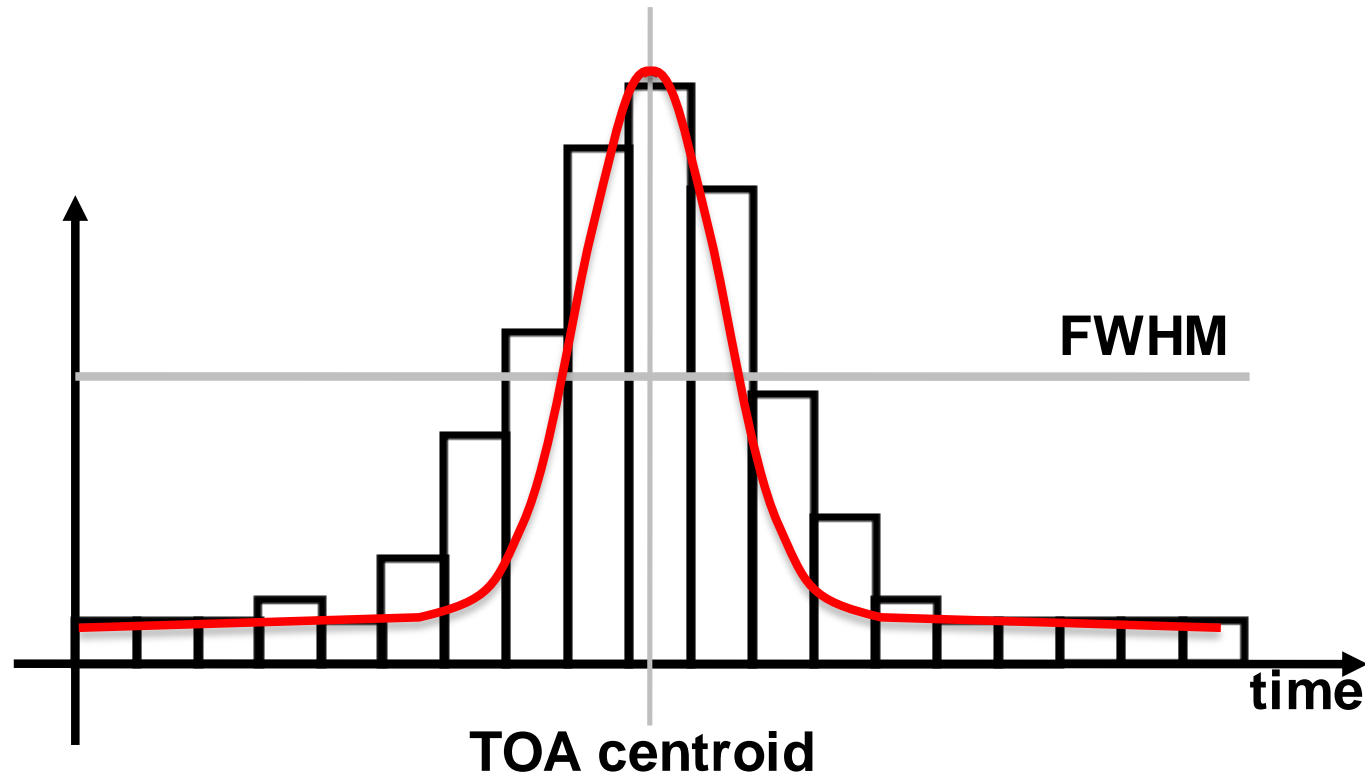
Homework 2: Design and analysis of a LIDAR system

- Design and analyse a simple Light Detection and Ranging (LIDAR) time-of-flight system, based on the discussion during the class (TDC application examples, Section 5.3.9):
 - a) Estimate the overall system parameters (target distance, characteristics such as reflectivity, background light, illuminator, detector, time-stamping electronics).
 - b) What is the typical PDF of the backscattered light?
 - c) How is it influenced by the precision of the individual components?
 - d) How can you increase the measurement precision? And its accuracy?
 - e) Suppose that you need to operate at a distance of up to 10 m. Which maximum laser pulse repetition rate can you use?

Homework 2: Reminder: 5.3.9 TDC Application Example: Time-of-Flight System



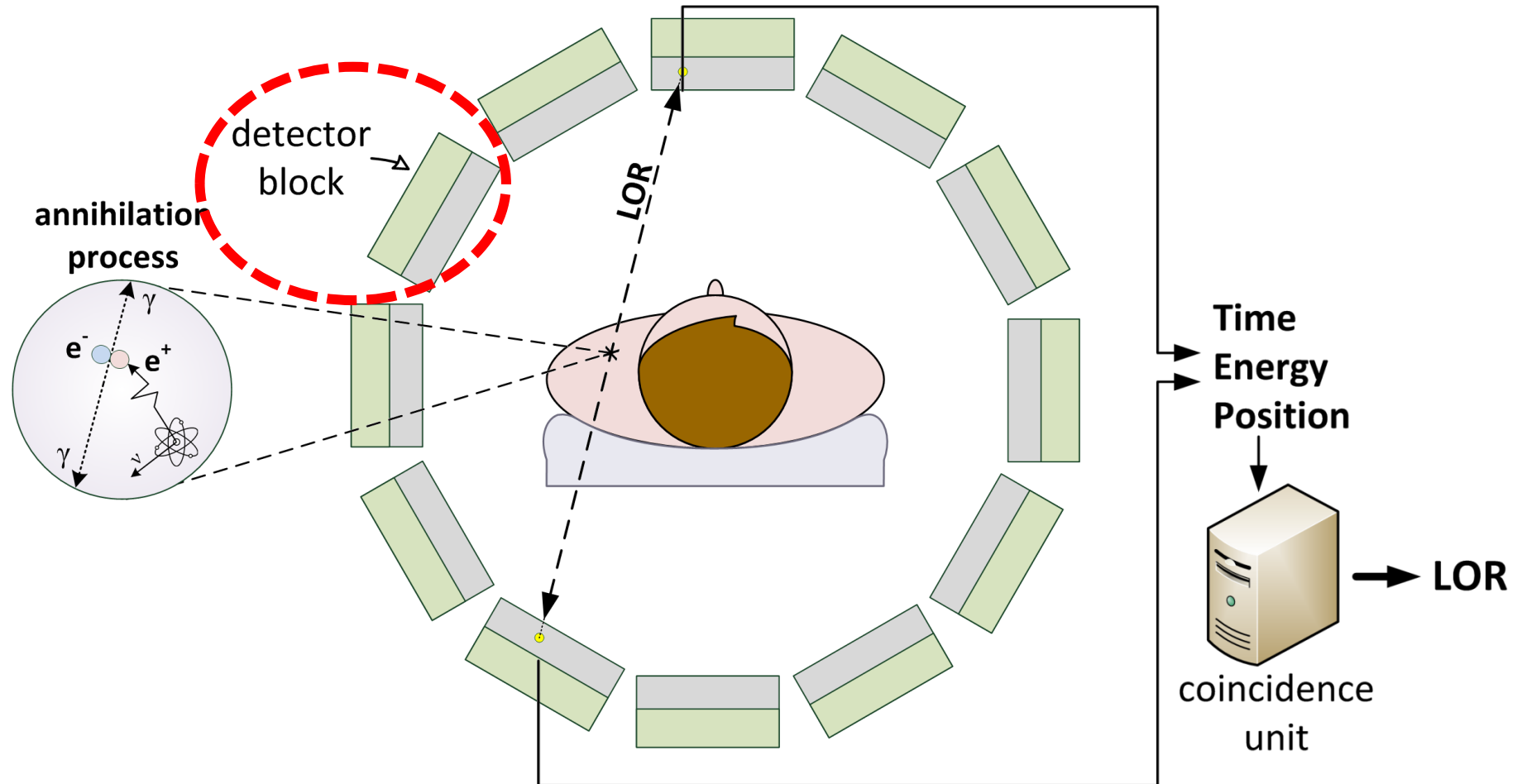
Homework 2: Reminder: 5.3.9 TDC Application Example: Time-of-Flight System



Homework 3: Design and analysis of a PET System

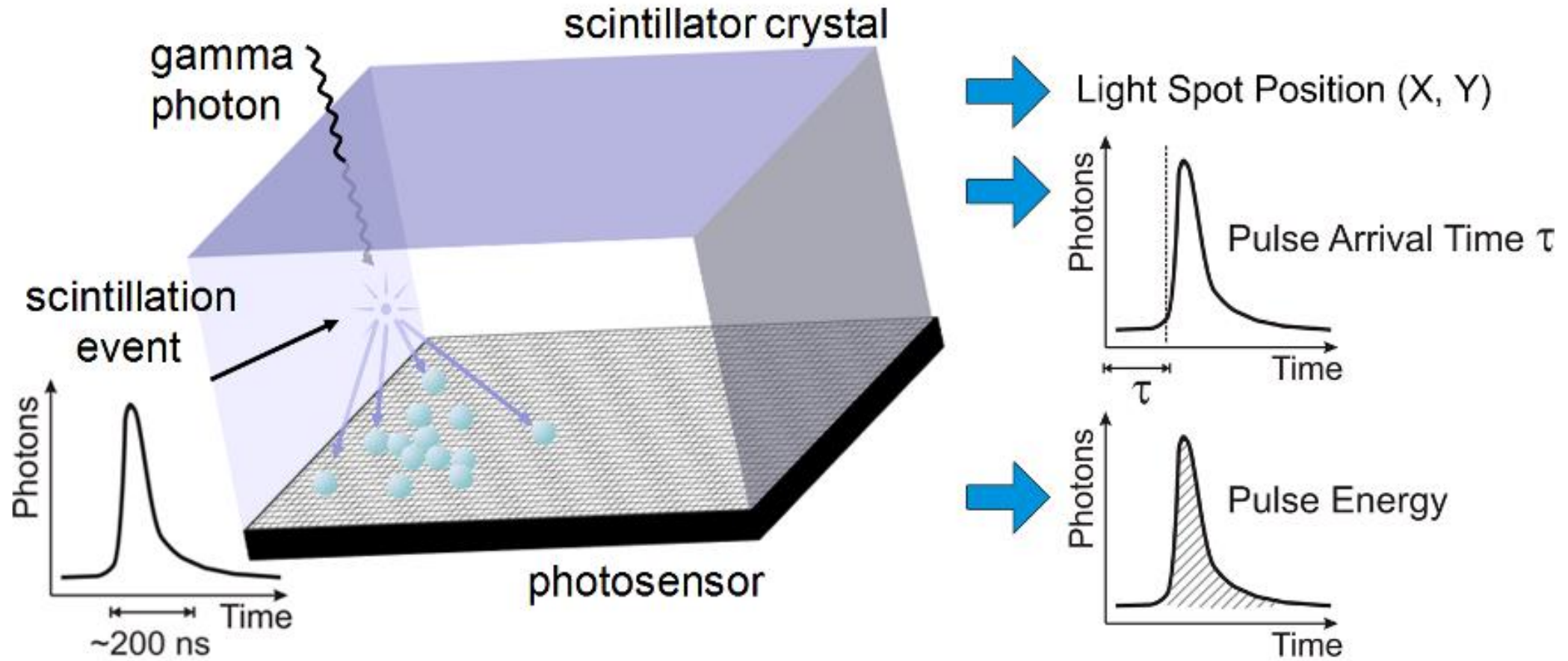
- Design and analyse a simple Positron Emission Tomography (PET) system:
 - a) How does the system work (in general terms)?
 - b) How does the photodetector module, coupled to a scintillator, work? Which main parameters must be estimated?
 - c) Which is the typical PDF of the scintillation light?
 - d) How much time does the scintillation light take to travel from the point of impact in the crystal to the photodetector?
 - e) Provide some examples of overall time of arrival estimators (estimation theory).

Homework 3: Design and analysis of a PET System



 GE Discovery IQ, Nov 2016

Homework 3: Design and analysis of a PET System



Homework 4: Design case study

Homework 4: Amplifier frequency response (1)

- For any electronic circuit we can derive a transfer function $A(s)$ by small-signal analysis to give


$$A(s) = \frac{N(s)}{D(s)} = \frac{a_0 + a_1 \cdot s + a_2 \cdot s^2 + \dots + a_m \cdot s^m}{1 + b_1 \cdot s + b_2 \cdot s^2 + \dots + b_n \cdot s^n}$$

Where a_0, a_1, \dots, a_m and b_1, b_2, \dots, b_n are constants.

- Very often the transfer function contains poles only (or the zeros are unimportant). In this case we can factor the denominator to give

$$A(s) = \frac{K}{\left(1 - \frac{s}{p_1}\right) \left(1 - \frac{s}{p_2}\right) \dots \left(1 - \frac{s}{p_n}\right)}$$

Where K is a constant and p_1, p_2, \dots, p_n are the poles of the transfer function.

 Paul R. Cova, "Analysis and design of analog integrated circuits, 5th edition."


Homework 4: Amplifier frequency response (2)

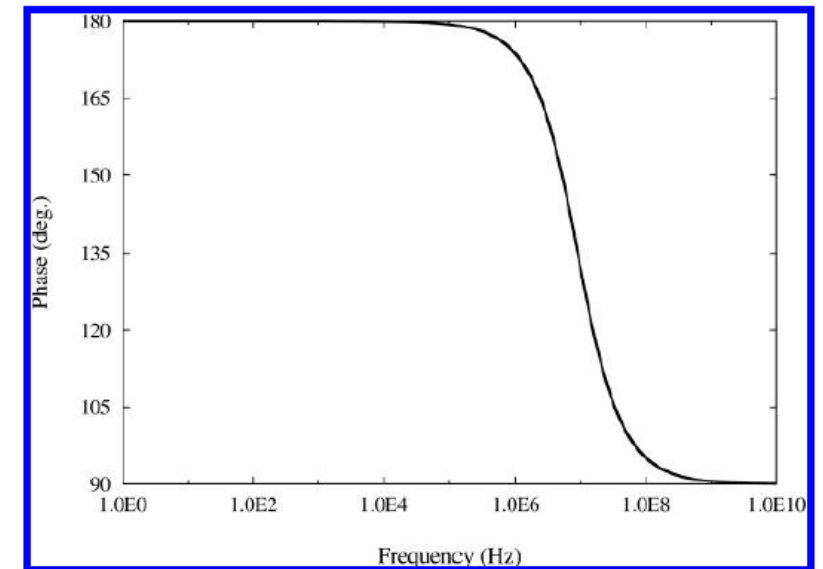
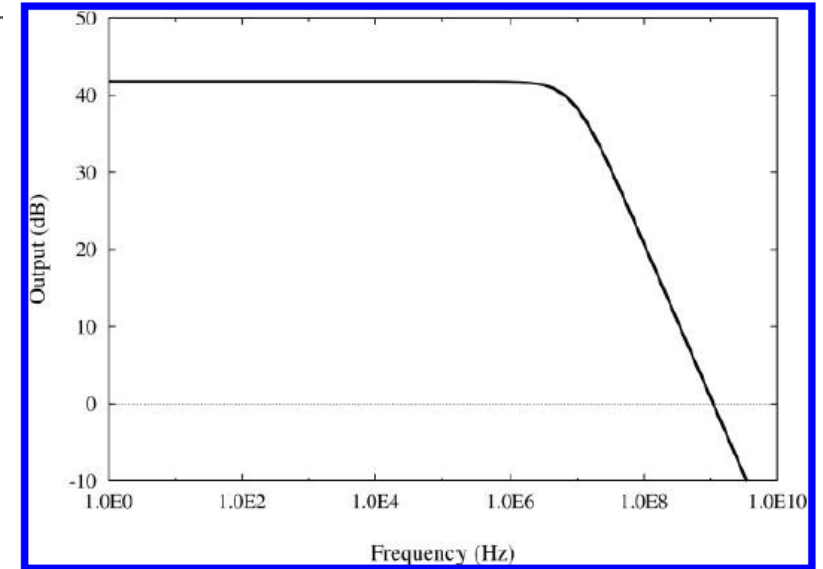
- An important case occurs when one pole is dominant. That is, when $|p_1| \ll |p_2|, |p_3|, \dots$
- The gain magnitude in the frequency domain can be approximated as

$$|A(j\omega)| \simeq \frac{K}{\sqrt{1 + \left(\frac{\omega}{p_1}\right)^2}}$$

This approximation can accurately predict the -3-dB frequency at least until $\omega \simeq |p_1|$, and we can write

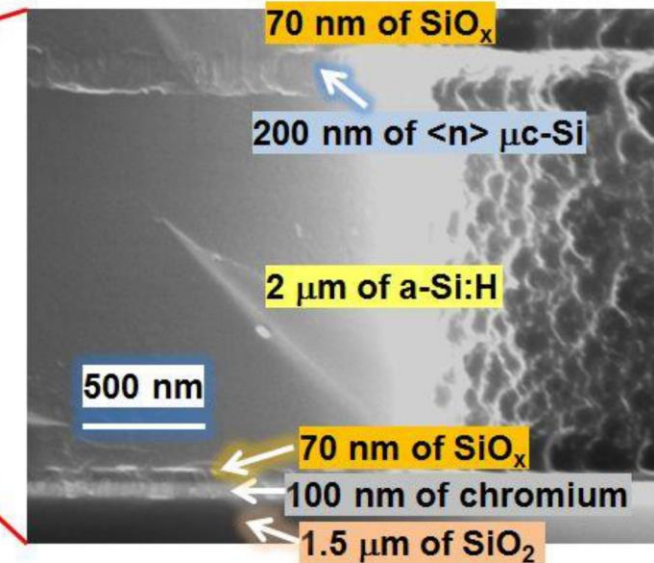
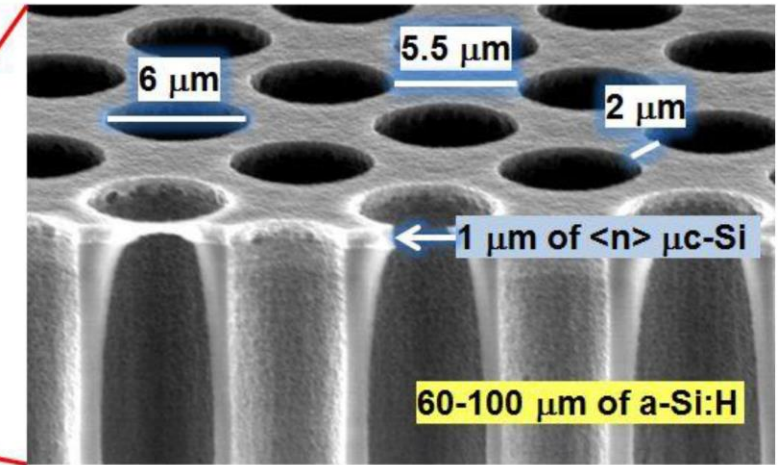
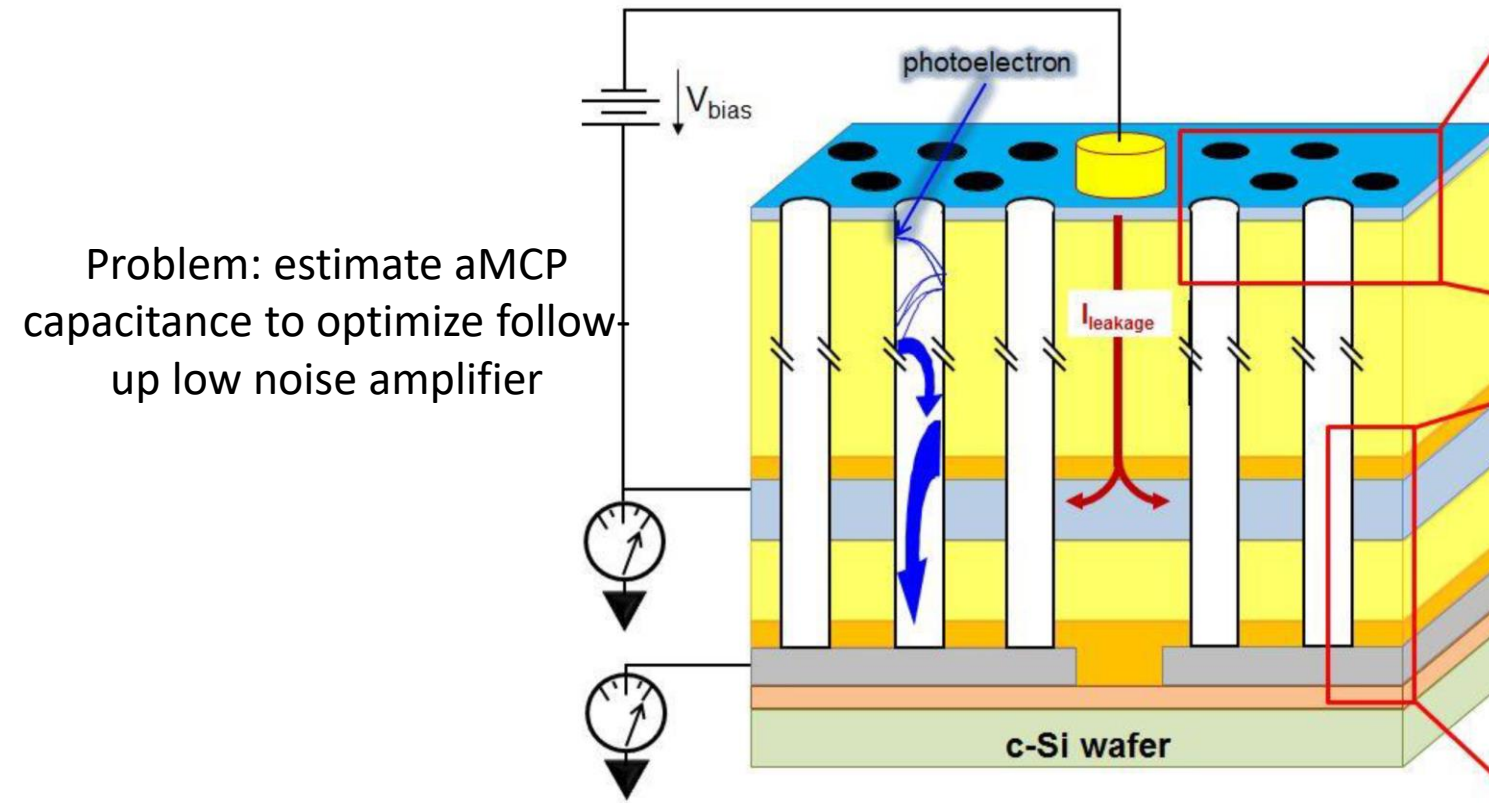
$$\omega_{-3dB} \simeq |p_1|$$

 Paul R. Cova, "Analysis and design of analog integrated circuits, 5th edition."



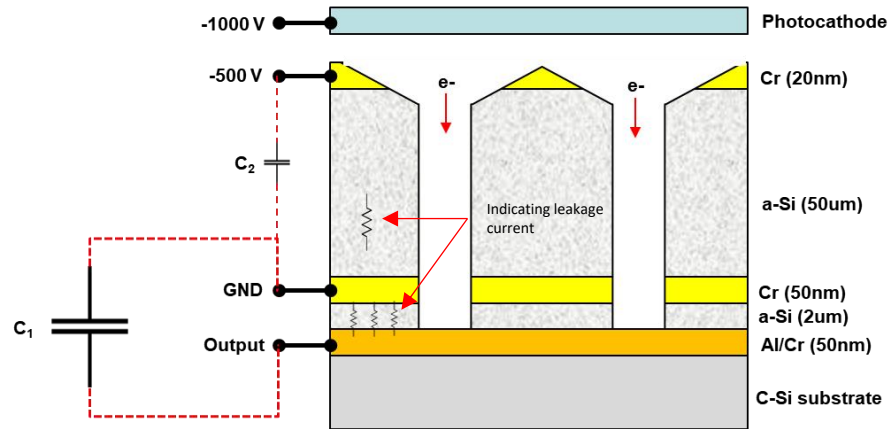
Homework 4: Design case study

Rendering and microscopic (SEM) view of an a-Si:H based Multi-Channel Plate (aMCP)

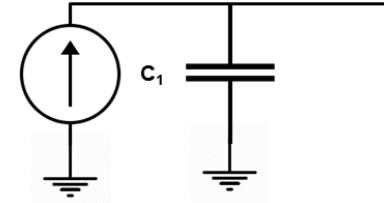
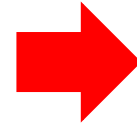


Frey, S., et al. "Characterization of Amorphous Silicon Based Microchannel Plates with High Aspect Ratio." 2019 IEEE NSS/MIC

Homework 4 : Design case study



Cross-section view of the aMCP channels



Simplified electrical model of AMCPs

$$C = \epsilon_r \epsilon_0 \frac{A}{d}$$

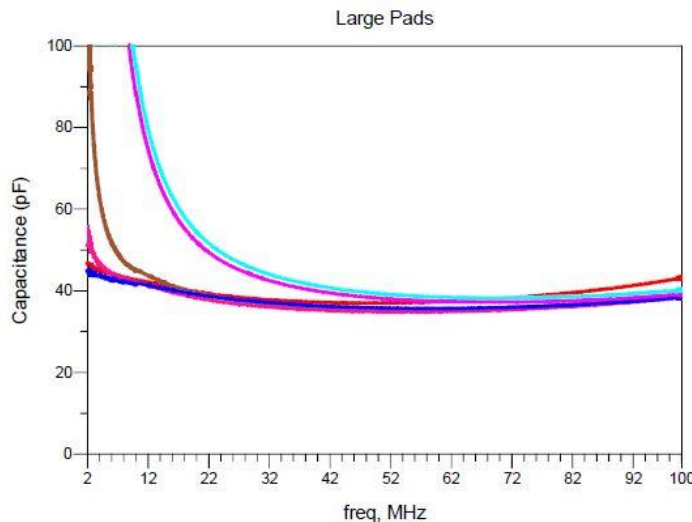
$$\epsilon_r \rightarrow \sim 12 \text{ for a-Si:H}^*$$



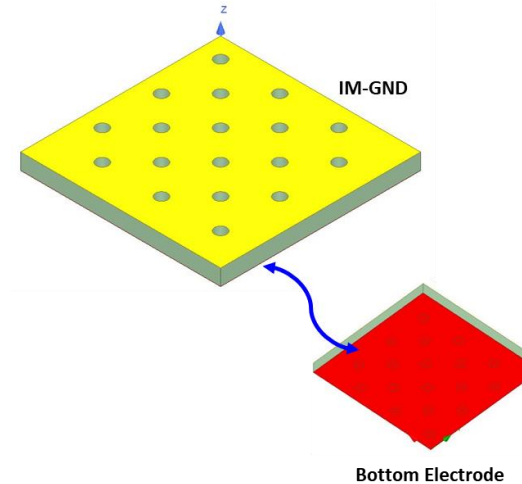
Estimation of AMCP capacitance via parallel plate capacitor
($\sim 960 \times 960 \mu\text{m}^2$) $\rightarrow C_1 \sim 45.5 \text{ pF}$



vs. ANSYS simulation
 $\rightarrow C_1 = 49.37 \text{ pF}$



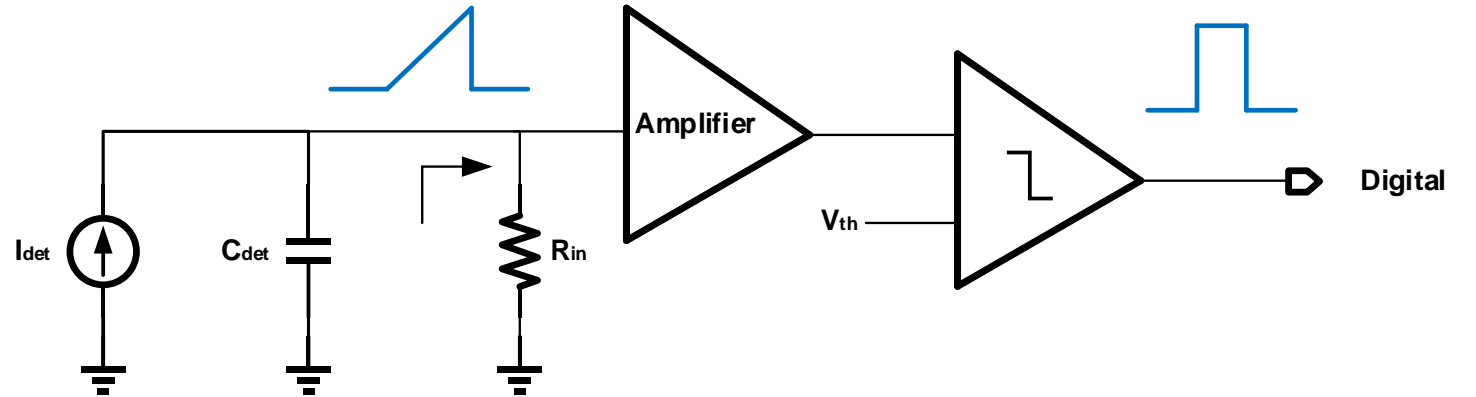
vs. Experimental results
(notice a few broken channels)



Homework 4 : Design case study

- Example of detector specifications:

$$\begin{aligned}Q_{in} &= 3000 \text{ e-} / 10000 \text{ e-} \\C_{det} &= 2 \text{ pF} \\t_{coll} &= 10 \text{ ps}\end{aligned}$$

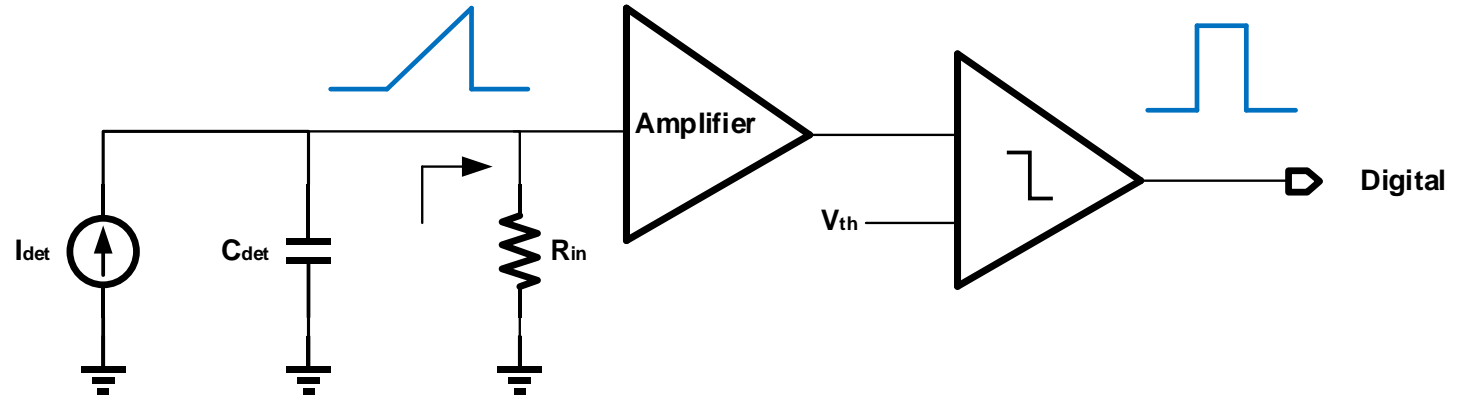


- *Exercise:* Estimate the pre-amplifier specifications:
 - a/ DC gain
 - b/ -3 dB bandwidth
- *Hint 1:* We always cover the worst case scenario when designing a read-out circuit.
- *Hint 2:* Assume a targeted rise time $t_{rise} = 30 \text{ ps}$ at the input of the comparator.

Homework 4: Design case study

$$\begin{aligned}Q_{in} &= 3000 \text{ e-} / 10000 \text{ e-} \\C_{det} &= 2 \text{ pF} \\t_{coll} &= 10 \text{ ps}\end{aligned}$$

- a/ DC gain



$$V_{in,min} = \frac{Q_{in,min}}{C_{det}} = 0.25 \text{ mV}$$

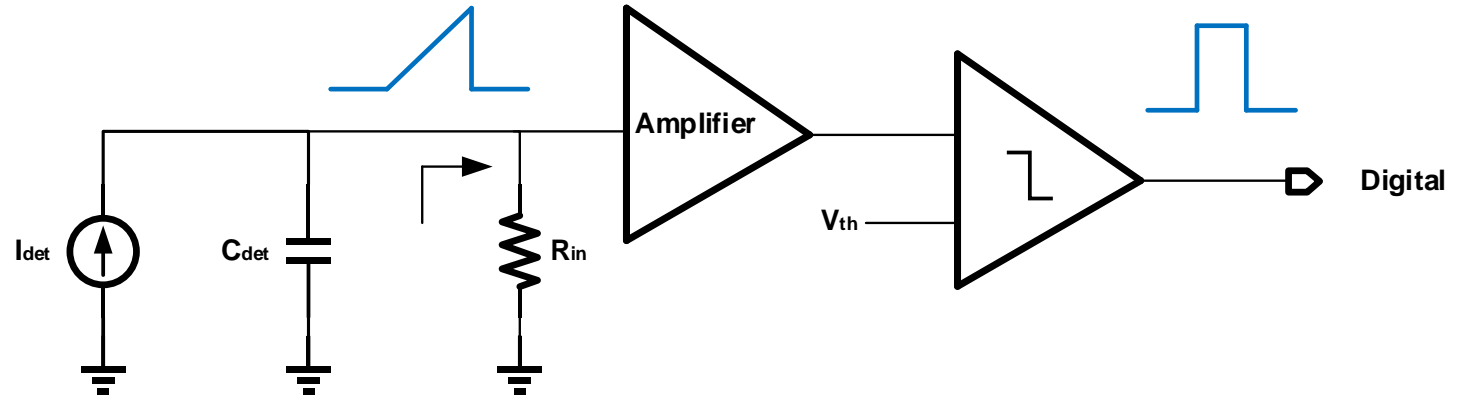
$$V_{out,min} = 1.5 \cdot V_{th,cmp}$$

$$A_{v,min} = \frac{V_{out,min}}{V_{in,min}} \approx 120$$

$$A_{v,min}(dB) = 20 \log(120) \approx 42 \text{ dB}$$

Homework 4: Design case study

$$\begin{aligned}Q_{in} &= 3000 \text{ e-} / 10000 \text{ e-} \\C_{det} &= 2 \text{ pF} \\t_{coll} &= 10 \text{ ps}\end{aligned}$$



- b/ -3 dB bandwidth

In case the collection time t_{coll} is smaller than the input RC constant, the rise time is higher than the collection time.

- The collected charges are integrated on the detector capacitance.

Homework 4: Design case study

$$\begin{aligned}Q_{in} &= 3000 \text{ e-} / 10000 \text{ e-} \\C_{det} &= 2 \text{ pF} \\t_{coll} &= 10 \text{ ps}\end{aligned}$$

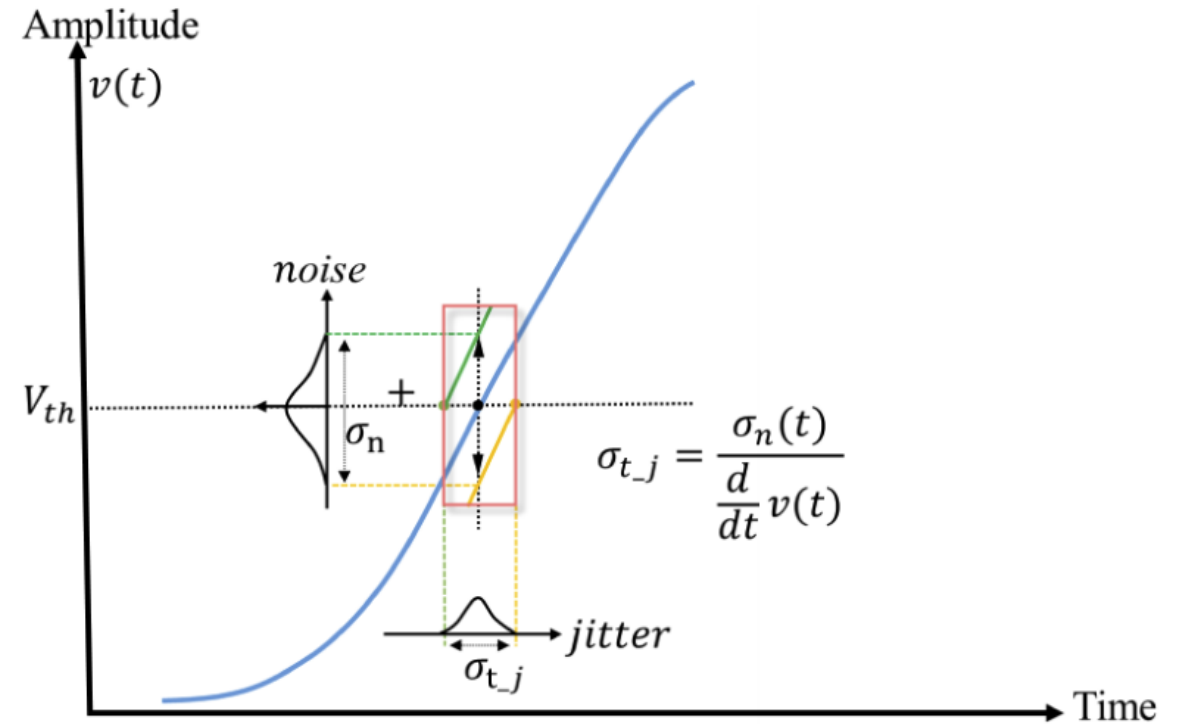
In order to make the comparator less sensitive to noise, the slope at its input should be as steep as possible (ideally $t_{rise} = t_{coll}$).


For our analysis:

$$t_{rise} = 30 \text{ ps}$$

$$f_{-3dB} \approx \frac{0.33}{t_{rise}}$$

$$f_{-3dB} \approx 11 \text{ GHz}$$



 J. Yang, G. Gu, W. Qian, K. Ren, D. Lu, J. Zhang, P. Guo, Q. Gao, M. Wan, and Q. Chen, "Pulsed light time-of-flight measurement based on a differential hysteresis timing discrimination method," Opt. Express 28, 23554-23568 (2020).